

Multi-label Conformal Prediction with a Mahalanobis Distance Nonconformity Measure

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The 13th Symposium on Conformal and Probabilistic Prediction with Applications
(COPA 2024)

September 9, 2024

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Introduction

Multi-label Classification Problem

Multi-label classification is a problem category in which each instance can belong to multiple classes simultaneously, resulting in the formation of label-sets.

Let $C = \{c_1, \dots, c_d\}$ denote the set of d individual classes, with each class indexed corresponding to an element of C . A label-set ψ is a subset of C ,

$$\psi \subseteq C.$$

Multi-label classification progress studies

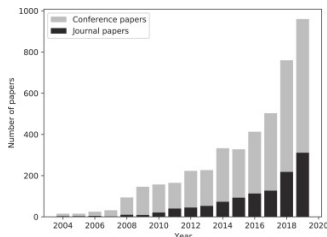


Figure: (Bogatinovski et al. 2022): A summary of the number of papers from the SCOPUS database related to the topic of Multi-label Classification. The vertical axis represents the number of conference and journal papers related to the topic per year.

Paper ([Wang et al. 2017](#)) published in *Proceedings of the IEEE conference*

“Chestx-ray8: Hospital-scale chest x-ray database and benchmarks on weakly-supervised classification and localization of common thorax diseases”

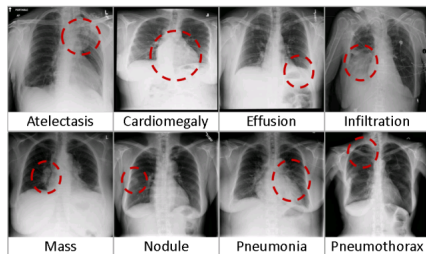


Figure 1. *Eight common thoracic diseases observed in chest X-rays that validate a challenging task of fully-automated diagnosis.*

Data: comprises 108,948 frontal-view X-ray images of 32,717 unique patients

Citations: more than 4000

Funding:

- Research Programs of the NIH Clinical Center and National Library of Medicine
- GPU donation by **NVIDIA Corporation**

Multi-label classification techniques fall into two major categories ([Tsoumakas and Katakis 2007](#)):

- Algorithm Adaptation (AA) methods:
Modified versions of multi-class machine learning techniques for predicting sets of labels.
- Problem Transformation (PT) methods:
Such as:
 - Binary Relevance (BR)
 - Instant Reproduction (IR)
 - Label Power-set (LP)

Differences LP-CP and other multi-label CP methods:

- 1 Calculation of nonconformity scores and p-values
- 2 Construction of prediction regions
- 3 Provided guarantee
- 4 Computational cost
- 5 Label dependencies and interactions

Example space symbolism

- Ψ denote a set of label-sets.
- X denote the feature space of which the inputs are represented as vectors of the form,

$$\vec{x}_i = (x_{i_1}, \dots, x_{i_s}),$$

where $X \cong \mathbb{R}^s$ and s is the number of attributes.

- Z denote example space,

$$Z = \{(x_i, \psi_i) : x_i \in X, \psi_i \in \Psi, i = 1, \dots, n\},$$

Training set partitioning

- proper-training set $\{(x_1, \psi_1), \dots, (x_q, \psi_q)\}$, where $q \leq n$.
- calibration set $\{(x_{q+1}, \psi_{q+1}), \dots, (x_n, \psi_n)\}$.

Nonconformity measure of the calibration instances

$$A : Z \rightarrow \mathbb{R} \text{ with } a_i = A\left(\{(x_1, \psi_1), \dots, (x_q, \psi_q)\}, (x_i, \psi_i)\right), i = q + 1, \dots, n.$$

Nonconformity measure of the test instances

Let \mathcal{Y}_j denote every assumed label-set for a test instance x_{n+m} .

$$a_{n+m}^{\mathcal{Y}_j} = A\left(\{(x_1, \psi_1), \dots, (x_q, \psi_q)\}, (x_{n+m}, \mathcal{Y}_j)\right)$$

Introduction

Inductive Conformal Prediction (ICP)

P-value p of each possible label \mathcal{Y}_j

$$p(\mathcal{Y}_j) = \frac{|i = q + 1, \dots, n : a_i \geq a_{n+m}^{\mathcal{Y}_j}| + 1}{n - q + 1}$$

Prediction regions for every test instance x_{n+m}

$$\Gamma_{x_{n+m}}^\varepsilon = \{\mathcal{Y}_j : p(\mathcal{Y}_j) > \varepsilon\}$$

We sort the calibration scores in descending order and we denote the ordered calibration scores as a_k^{desc} , for $k = 1, \dots, n - q$, where $a_1^{desc} < \dots < a_{n-q}^{desc}$.

Proposition:

For some value ε of the significance level, the minimum integer of which the inequality,

$$\left| \{i = q + 1, \dots, n : a_i^{desc} \geq a_{k_\varepsilon}^{desc}\} \right| > \varepsilon(n - q + 1) - 1,$$

holds is,

$$k_\varepsilon = \lfloor \varepsilon(n - q + 1) \rfloor.$$

Given k_ε , the prediction sets for each instance x_{n+m} at the ε significance level are written in the equivalent form,

$$\Gamma_{x_{n+m}}^\varepsilon = \{\mathcal{Y}_j : a_{n+m}^{\mathcal{Y}_j} \leq a_{k_\varepsilon}^{desc}\}.$$

Multi-label ICP using Mahalanobis measure

Multi-hot label representation

Let $\mathcal{P}(\mathcal{C}) = \{\mathcal{Y}_j : \mathcal{Y}_j \subseteq \mathcal{C}\}$ denote the power-set generated by all combinations of classes.

For every label-set $\mathcal{Y}_j \in \mathcal{P}(\mathcal{C})$, we construct a multi-hot vector $\vec{y}_j = (y_{j_1}, \dots, y_{j_c}, \dots, y_{j_d})$ as follows,

$$y_{j_c} = \begin{cases} 0, & \text{if } c \notin \mathcal{Y}_j \\ 1, & \text{if } c \in \mathcal{Y}_j \end{cases}, \text{ for every } c \in \mathcal{C}.$$

Thus, we create a bijection, $\sigma : \mathcal{P}(\mathcal{C}) \rightarrow Y$, between the power-set $\mathcal{P}(\mathcal{C})$ and the formed subspace $Y \subseteq \mathbb{R}^d$ of the vectors \vec{y}_j .

Notes:

- The empty set in $\mathcal{P}(\mathcal{C})$ corresponds to the zero vector.
- The number of possible multi-hot vectors in Y equals the number 2^d of possible label-sets in $\mathcal{P}(\mathcal{C})$.

Multi-label ICP using Mahalanobis measure

Error space

Denote $\vec{o} = \vec{o}(x)$ the predicted probabilities of classifier, for an instance x , where $o \in \mathbb{R}^d$.

We define the linear transformation $r : \mathbb{R}^d \times \{\vec{o}(x)\} \rightarrow \mathbb{R}^d$ with,

$$r(\vec{y}, \vec{o}(x)) = |\vec{y} - \vec{o}(x)|.$$

Definition

We define $\vec{r}_i^{y_j} = (r_{i_1}, \dots, r_{i_d})$ as the error vector for instance i related to label-set y_j , such that

$$\vec{r}_i^{y_j} = (|y_{j_1} - o_{i_1}|, \dots, |y_{j_d} - o_{i_d}|),$$

where $\vec{o}_i = (o_{i_1}, \dots, o_{i_d})$, with $o_{i_k} \in [0, 1]$, $k = 1, \dots, d$.

Notes:

- The error vectors constitute a subspace R of \mathbb{R}^d .
- The linear map r is injective, and thus the label-space Y and the error space R are isomorphic.
- The choice of defining error vectors in Euclidean vector space provides a connection between the probabilistic outputs of the underlying classifier and the label-sets.

Multi-label ICP using Mahalanobis measure

Distances nonconformity measures

Let \vec{y}_j denote the true label for calibration instances and assumed label for the test instances.

Euclidean Distance (Norm) nonconformity measure

Maltoudoglou et al. 2022 define a nonconformity measure, for an instance i , using Euclidean Distance as,

$$\alpha_i^{y_j} = \sqrt{r_{i_1}^2 + \dots + r_{i_d}^2}.$$

Mahalanobis Distance nonconformity measure

Definition

Based on the Mahalanobis distance, we define the non-conformity measure of the error vectors for a calibration instance i as,

$$\alpha_i^{y_j} = \sqrt{(\vec{r}_i^{y_j})^T \Sigma^{-1} \vec{r}_i^{y_j}}$$

where Σ^{-1} is the inverse covariance matrix which is estimated from error vectors of the proper training data.

Note:

- The covariance matrix takes into account the correlation of the error vectors.
- The Mahalanobis distance is a transformation of the Euclidean distance achieved by using the covariance matrix.
- Σ is symmetric and positive definite.

Multi-label ICP using Mahalanobis measure

Algorithm

Algorithm: Multi-label ICP using Mahalanobis measure

Input:

- Classifier's predicted probabilities for proper-training data $\vec{o}(x_i)$, $i = 1, \dots, q$, for calibration data $\vec{o}(x_i)$, $i = q + 1, \dots, n$, for each test instance $\vec{o}(x_{n+m})$.
- Label-sets of proper-training data \vec{t}_i , $i = 1, \dots, q$, of calibration data \vec{t}_i , $i = q + 1, \dots, n$.
- Required significance level ε .

Steps:

1 Preprocessing on proper-training data:

- Calculate the error vectors $\vec{r}_i = |\vec{o}_i - \vec{t}_i|$, $i = 1, \dots, q$.
- Form the covariance matrix Σ .

2 Preprocessing on calibration data:

- Calculate the error vectors $\vec{r}_i = |\vec{o}_i - \vec{t}_i|$, $i = q + 1, \dots, n$.
- Calculate the calibration nonconformity scores a_i , $i = q + 1, \dots, n$, using $\alpha_i^{t_j} = \sqrt{(\vec{r}_i^{t_j})^T \Sigma^{-1} \vec{r}_i^{t_j}}$.
- Sort calibration scores in descending order a_k^{desc} , $k = 1, \dots, n - q$.
- Calculate k_ε using $k_\varepsilon = \lfloor \varepsilon(n - q + 1) \rfloor$.

3 Calculate scores $a_{n+m}^{y_j}$, for every possible label-set $\vec{y}_j \in Y$, using $\alpha_i^{y_j} = \sqrt{(\vec{r}_i^{y_j})^T \Sigma^{-1} \vec{r}_i^{y_j}}$.

Output:

Predicted set, $\Gamma_{x_{n+m}}^\varepsilon = \{\vec{y}_j \in Y : a_{n+m}^{y_j} \leq a_{k_\varepsilon}^{desc}\}$.

Emotions and Yeast datasets

Dataset	Instances	Attributes	Labels	Cardinality
Emotions	593	72	6	1.868
Yeast	2417	103	14	4.237

Multi-layer Perceptron (MLP) model

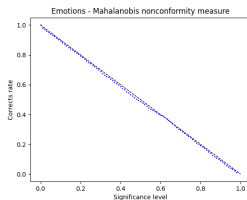
- multiple five fully connected layers
- activation function relu is defined in each layer
- the sigmoid activation function is defined for the probabilistic outputs
- early stopping is set up to avoid overfitting

Dataset partitioning

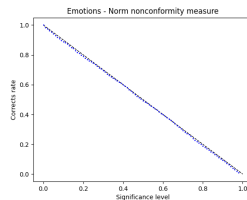
	Proper train	Validation	Calibration	Test
Emotions	354	81	99	59
Yeast	1293	327	555	242

Note:

Our experiments were performed following a 10-fold cross-validation process, which was repeated 10 times. The results were calculated as the average over all folds and repetitions.

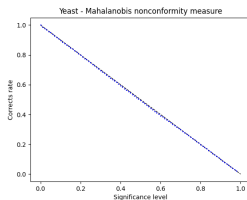


(a) Mahalanobis coverage per level ε

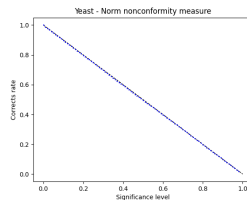


(b) Norm coverage per level ε

Figure 2: Mahalanobis and Norm coverage for Emotions dataset.



(a) Mahalanobis coverage per level ε



(b) Norm coverage per level ε

Figure 3: Mahalanobis and Norm coverage for Yeast dataset.

Table 1: Emotions dataset - Performance metrics

	MLP-classifier	ICP-Mahalanobis	ICP-Norm
Hamming loss	0.329	0.343	0.343
Accuracy	0.040	0.039	0.039
F1 Micro	0.226	0.246	0.246
F1 Macro	0.103	0.123	0.123
Average confidence	-	0.080	0.067
Average credibility	-	0.948	0.958

Table 2: Yeast dataset - Performance metrics

	MLP-classifier	ICP-Mahalanobis	ICP-Norm
Hamming loss	0.198	0.200	0.200
Accuracy	0.186	0.158	0.158
F1 Micro	0.644	0.628	0.628
F1 Macro	0.380	0.336	0.336
Average confidence	-	0.203	0.205
Average credibility	-	0.851	0.822

Note: The performance results indicate that no substantial classification performance is sacrificed by the use of ICP.

Table: Mahalanobis and Norm S-criterion comparison

	Mahalanobis	Norm
Emotions	547.005	560.869
Yeast	30922.511	81839.323

Figure: Mahalanobis and Norm N-Criterion - Graph comparison.

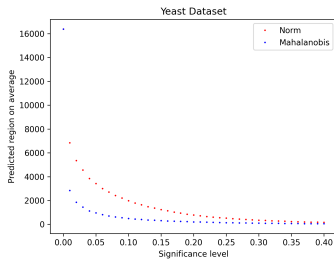
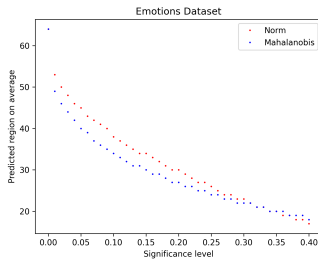


Table: Mean prediction region size as a percentage of the number of possible label-sets

Emotions dataset			Yeast dataset		
Level	Mahala (%)	Norm (%)	Level	Mahala (%)	Norm (%)
0.01	77	83	0.01	17	42
0.05	62	70	0.05	6	21
0.10	53	59	0.10	3	12
0.20	42	47	0.20	1	5

Note:





- The number of possible label-sets is 64 and 16.384 for the Emotions and Yeast dataset, respectively.
- In all cases, the Mahalanobis measure produces smaller regions with the values for the Yeast dataset demonstrating an impressive reduction.

Conclusions

- The vectors in the error space are injectively mapped to the label-sets space, rendering the conformal predictor associated with the Mahalanobis measure valid.
- The covariance matrix considers correlations between error vectors and thus results in higher informational efficiency compared to the Euclidean distance nonconformity measure.
- The prediction region sizes per significance level using the action of Mahalanobis measure is significantly smaller than that of the Norm measure.

Future work

- Formulate the calculation of nonconformity scores based on the nonconformity score of the predicted label-set.
- Develop an approach for efficiently calculating prediction regions (without calculating all p-values)
- Further explore the application of Mahalanobis nonconformity measure.
- Examine the formulation of a more informative ways of presenting the outputs.

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